



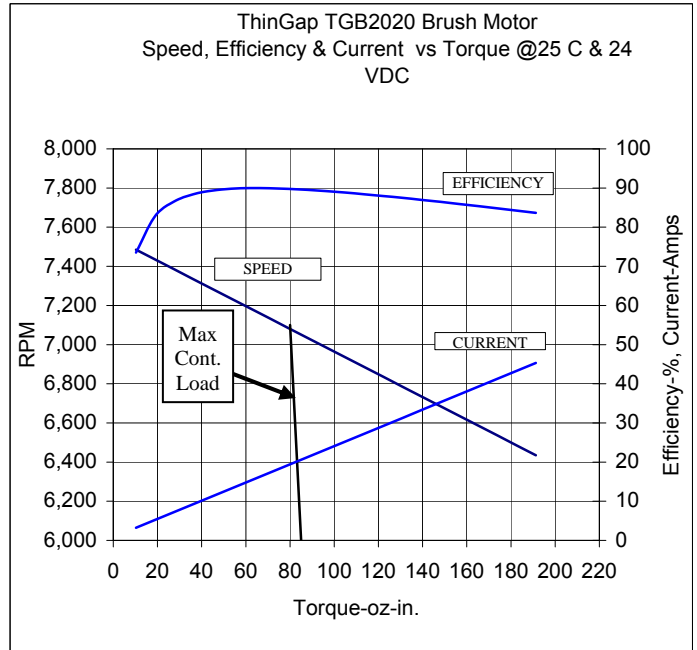
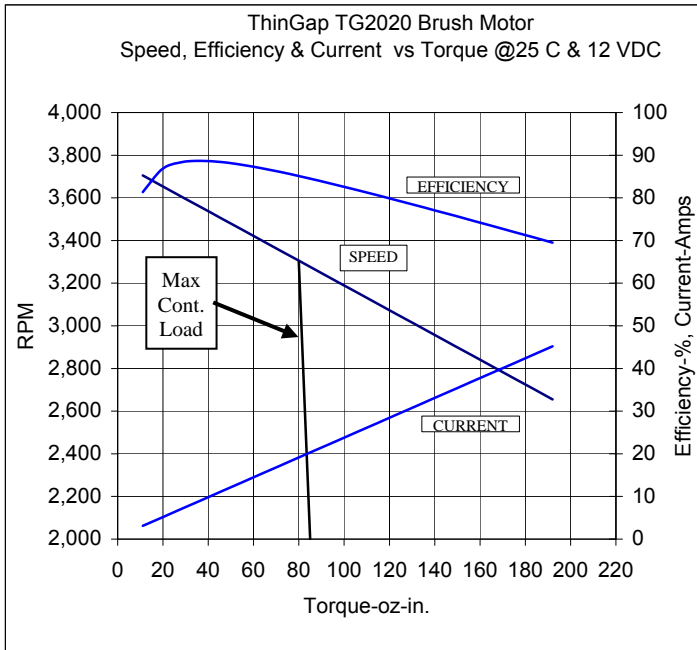
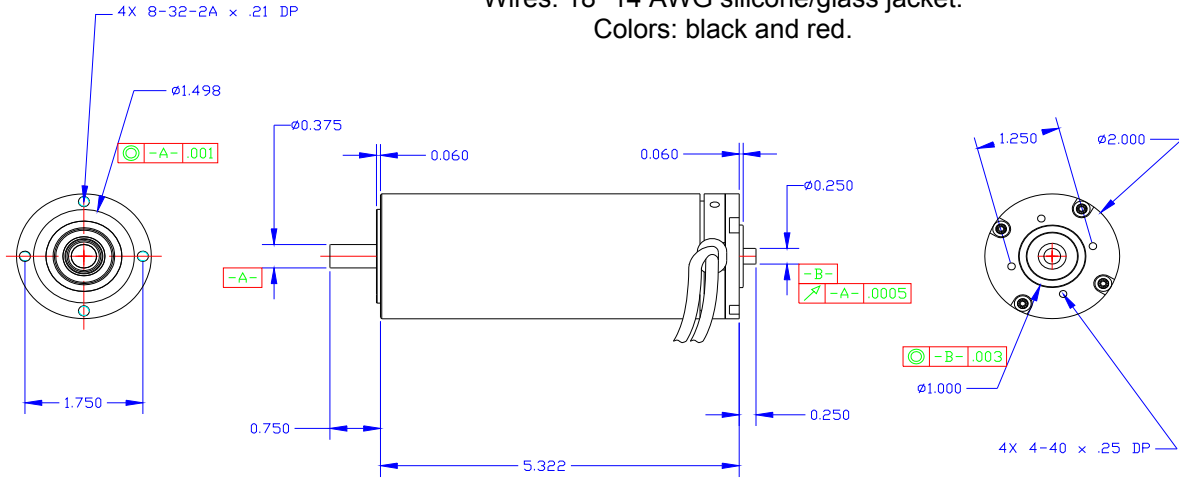
- High power density
- High efficiency
- Ironless core
- Zero cogging
- Zero hysteresis
- Zero iron losses
- Zero lamination ringing
- Rapid acceleration
- Low-inductance armature

### TGB2020 BRUSH MOTOR

Peak torque ( $T_{peak}$ )	425 oz-in.
Continuous shaft power ( $P_{cont}$ )	440 W
Voltage ( $V_{cont}$ )	24 V <sub>DC</sub>
Speed ( $\omega_{cont}$ )	7,407 rpm
Torque ( $T_{cont}$ )	80 oz-in.
Current ( $I_{cont}$ )	20.4 amps
Max efficiency @ 25 °C	90%
Max speed ( $\omega_{max}$ )	12,000 rpm
No load speed ( $\omega$ )	7,565 rpm @ 24 V <sub>DC</sub>
No load current ( $I_0$ )	0.80 amps @ 24 V <sub>DC</sub>
Motor constant ( $K_m$ )	15.2 oz-in./sqrt (W)
Motor constant/inertia ratio ( $K_m/J$ )	1,500/s [sqrt (W)]
Torque constant ( $K_t$ )	4.29 oz-in./amp
Back EMF constant ( $K_e$ )	352 rpm/V
Terminal resistance ( $R_t$ )	0.08 $\Omega$
Cogging and hysteresis torque ( $T_c$ )	0 oz-in.
Viscous drag torque ( $T_{ac}$ )	0.34 oz-in./krpm
Friction torque ( $T_{fr}$ )	1.0 oz-in.
Max armature temperature*	110 °C
Thermal resistance (TPR)	1.49 deg °C/W
Armature inductance (L)	4 $\mu$ H
Starting current (I)	0.23 amps @ 0.1 V <sub>DC</sub>
Armature weight ( $W_a$ )	8.3 oz
Motor weight ( $W_t$ )	53 oz
Armature inertia (J)	$9.07 \times 10^{-3}$ oz-in.-s <sup>2</sup>
*Max continuous winding temperature is limited by maximum magnet temperature of 120 °C. Peak power is limited by the temperature rise of the armature. Magnet material: Neodymium. Bearing type: Ball. Brush: Silver graphite. Poles: 2. Motor testing performed at 25 °C ambient with mounting heat sink of 3" x 3/8" x 8" aluminum.	

Outline Drawing

Wires: 18" 14 AWG silicone/glass jacket.  
Colors: black and red.



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